## Offline Programming Software

### **DENSO**

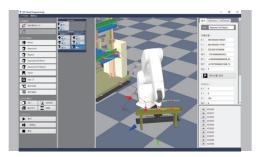
# **WINCAPS Plus**



Robot Viewer

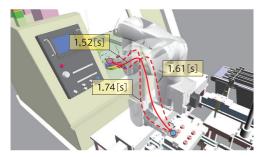
**Palletizing Builder** 

#### **3D Visual Programming**



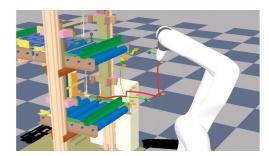
By enabling to place the flow control statements (conditional branches) visually on the trajectly, Users not familiar with the robot programming language can recognize the robot movement and easily write the codes.

#### **Optimal Motion Planner**



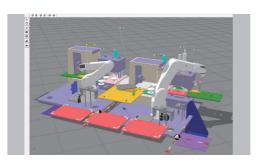
By specifying the start and the end points for the robot movement, the trajectory avoiding obstacles with the shortest cycle time is automatically generated. The trajectory generation that relies on the skilled users' experience is now scientifically performed, so that both skilled users and beginners can extract the the same performance from the robots.

#### **Home Position Guidance**



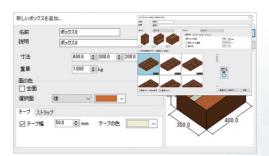
"Home Position Guidance" generates the path to safely go back to Home Position, assuming no obstacles on the paths the robot recorded during the automatic mode.

#### **Robot Viewer**



"Robot Viewer" is the 3D Viewer used in WINCAPS Pllus. Enhanced 3D CAD data loading, object operating environment, and object management enables WINCAPS Plus products to provide a comfortable simulation environment.

#### **Palletizing Builder**



"Palletizing Builder" is the software used for palletizing and depalletizing. The target position considering the movable range is automatically displayed by entering the shape and dimensions of the pallet and work. It is also possible to handle the multiple shapes and sizes of works.





Please visit our website for more information on products and functions.

https://www.denso-wave.com/





Official DENSO WAVE Channel:

Provides explanatory videos of functions, case studies, and robot applications.



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